
Computational Geometry

Definition, Application Areas, and
Course Overview

Computational Geometry

- is a subfield of the *Design and Analysis of Algorithms*



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 - deals with efficient data structures and algorithms for geometric problems
 - is only about 30 years old
 - started out by developing solid theoretical foundations, but became more and more applied over the last years
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Application Areas

- Computer Graphics
 - Computer-aided design / manufacturing
 - Telecommunication
 - Geology
 - Architecture
 - Geographic Information Systems
 - VLSI design (chip layout)
 - ...
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This course

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 - important algorithms and data structures
 - design patterns
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 - does not require you to program anything
 - requires you to solve homeworks in a careful mathematically correct way
-

Surface Reconstruction

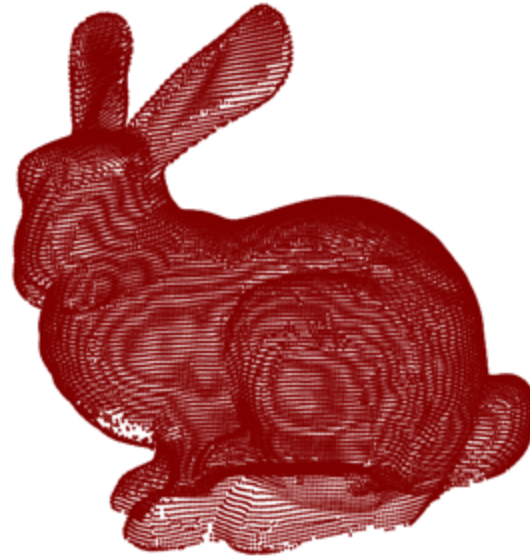
- Digitizing 3-dimensional objects



Stanford Bunny

Surface Reconstruction

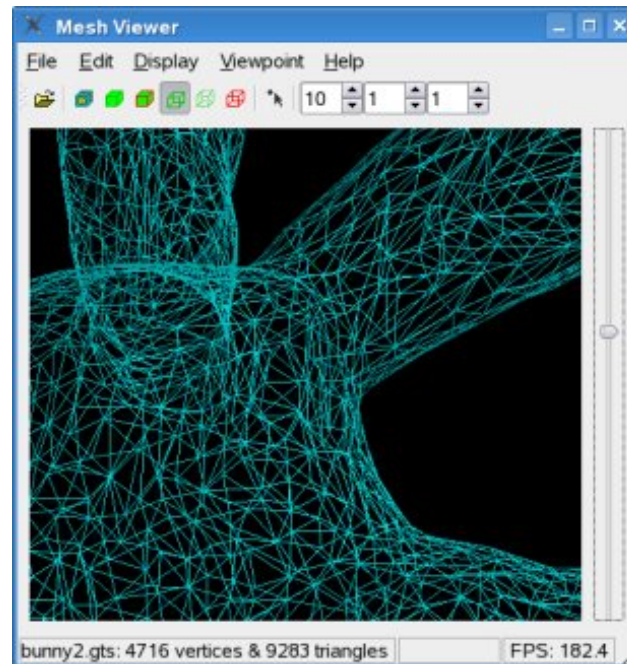
- Step 1: Scan the object (3d laser scanner)



set of points in \mathbf{R}^3

Surface Reconstruction

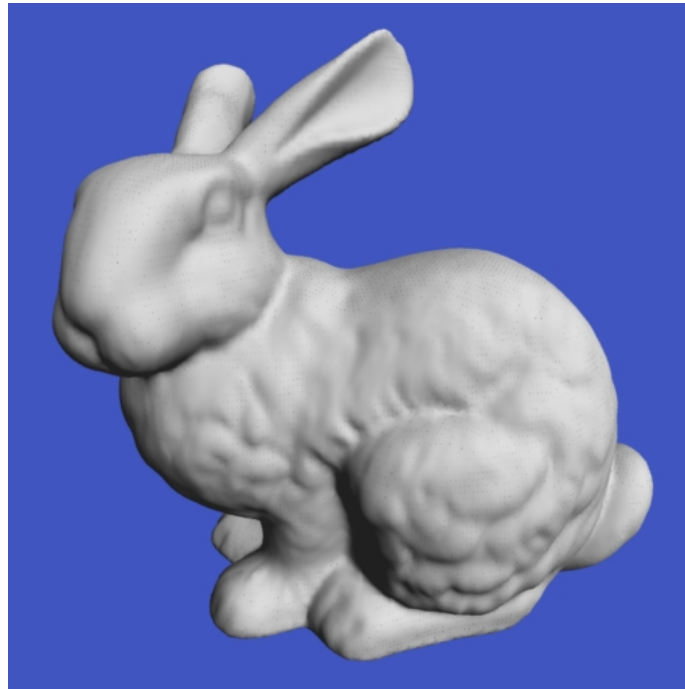
- Step 2: Create a triangulation



set of triangles in \mathbf{R}^3

Surface Reconstruction

- Step 3: process the triangulation (rendering)



smooth surface in \mathbf{R}^3

Surface Reconstruction

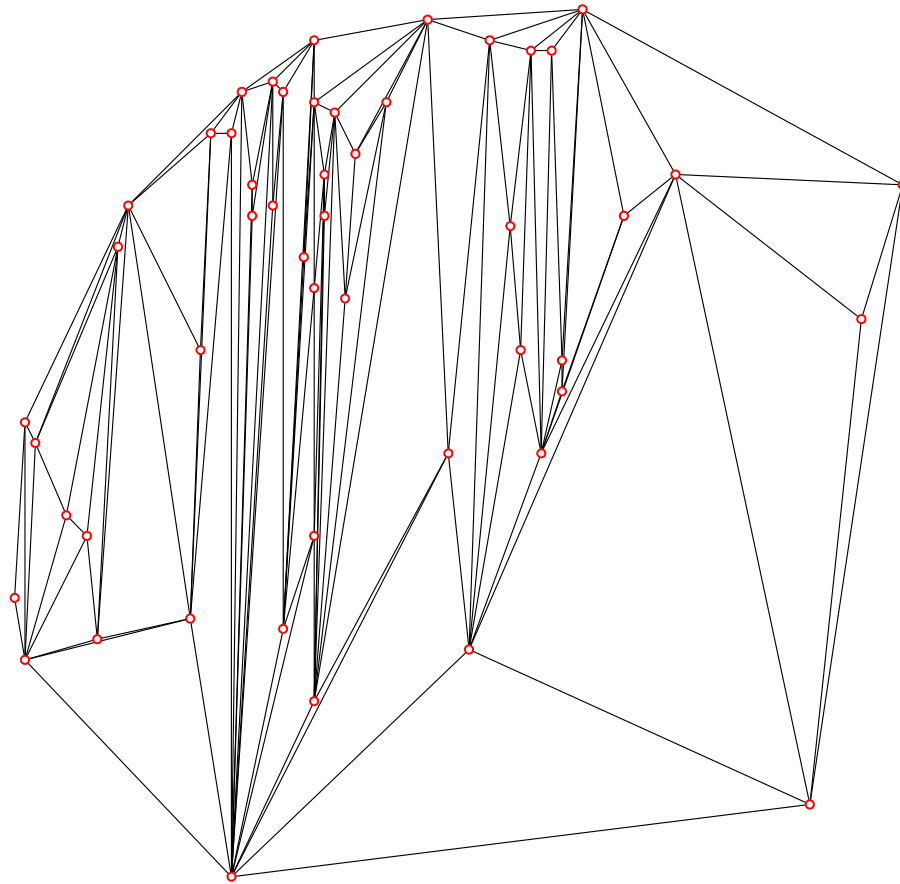
- Major Computational Geometry task:
 - Create a “good” triangulation



In this Course:

Good and bad triangulations in R^2

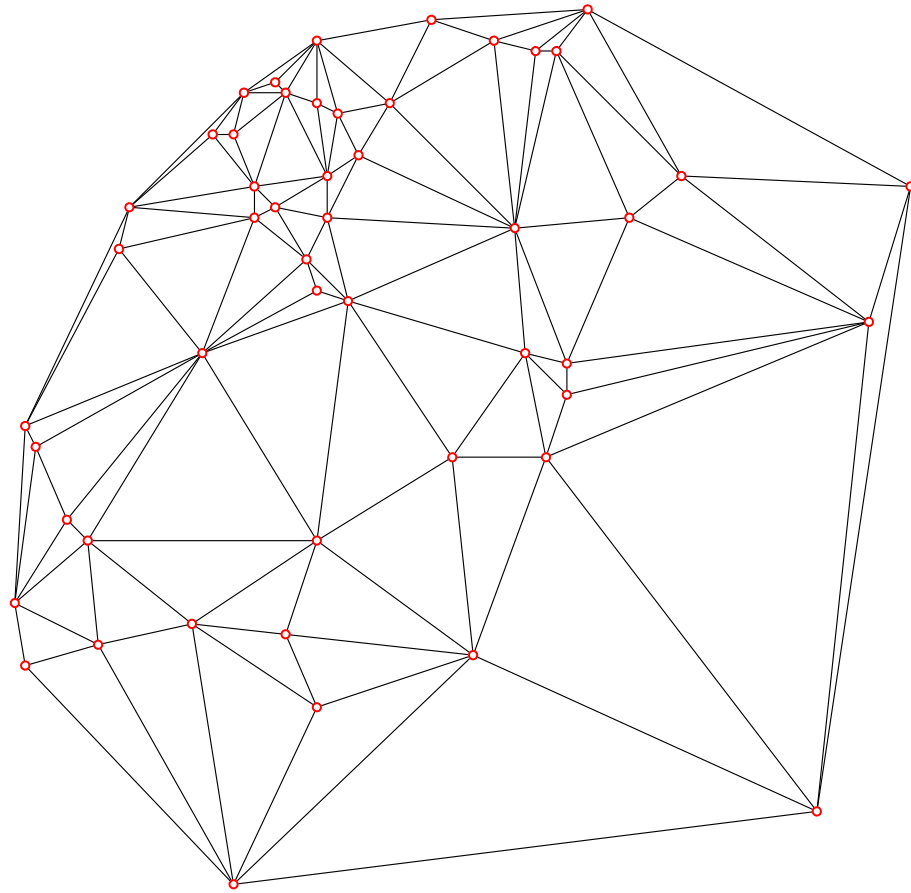
bad triangulation
(long and skinny
triangles)



In this Course:

Good and bad triangulations in R^2

good triangulation
(no small angles,
almost regular
triangles)



Collision detection

Check whether two (possibly complicated) 3d objects intersect!



Collision detection

- Bounding volume heuristic:
 - Approximate the objects by simple ones that enclose them (bounding volumes)



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Collision detection

- Bounding volume heuristic:
 - Approximate the objects by simple ones that enclose them (bounding volumes)
 - popular bounding volumes: boxes, spheres, ellipsoids,...
 - if bounding volumes don't intersect, the objects don't intersect, either
 - *only* if bounding volumes intersect, apply more expensive intersection test(s)
-

In this Course:

Smallest enclosing ball

- Given: finite point set in \mathbf{R}^d



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Smallest enclosing ball

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- Wanted: the smallest ball that contains all the points



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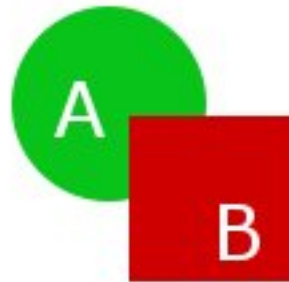
popular free software (also some commercial licenses sold):

<http://www.inf.ethz.ch/personal/gaertner/miniball.html>



Boolean Operations

- Given two (2d,3d) shapes, compute their...



Intersection



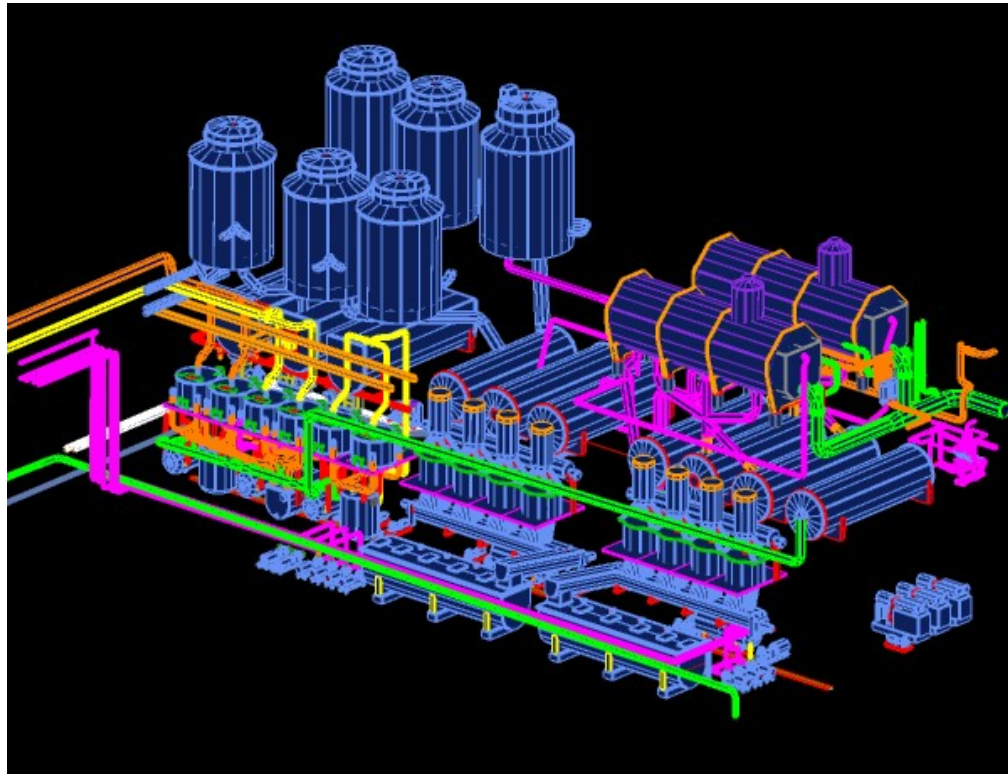
Subtraction



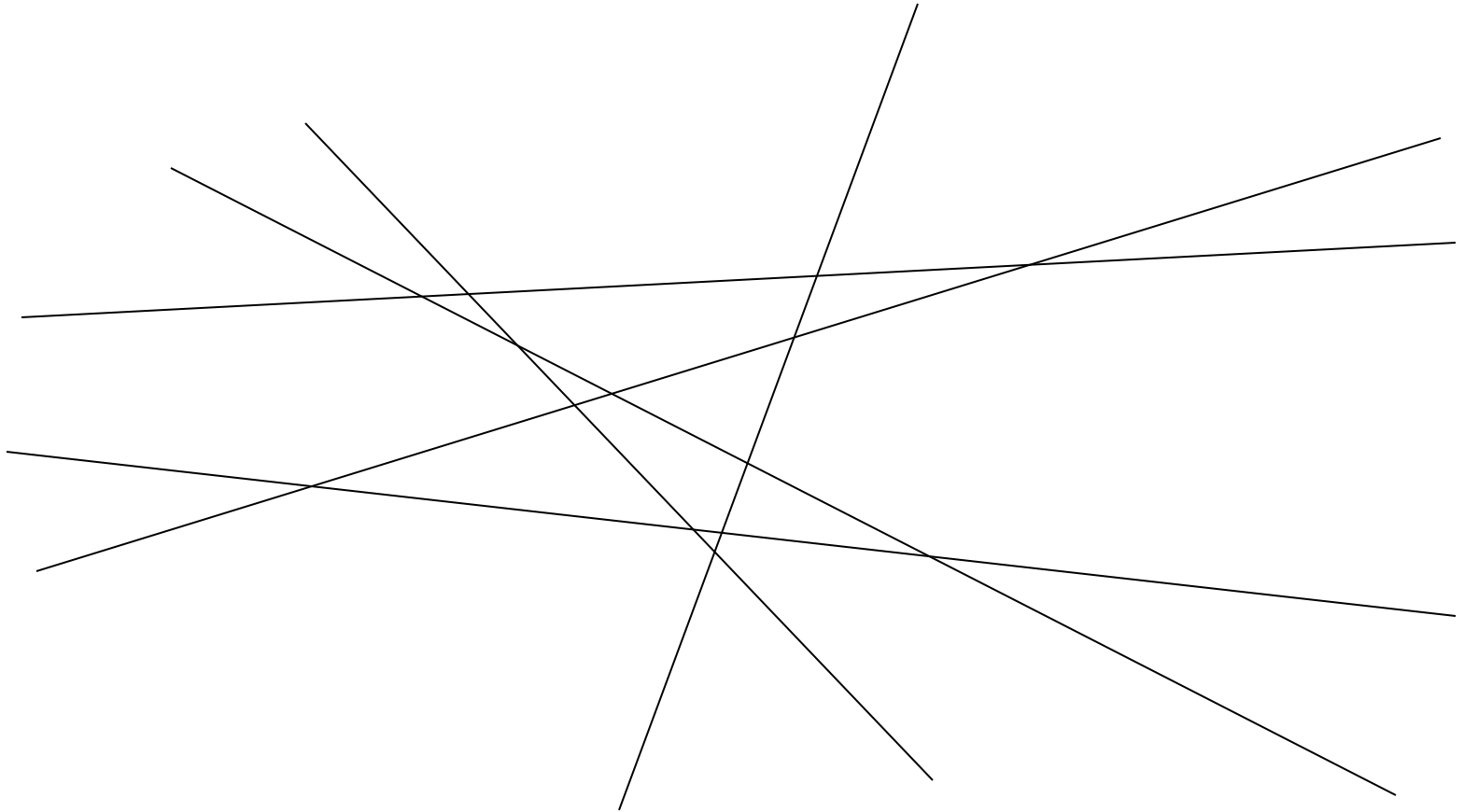
Union

Boolean Operations

- ubiquitous in *computer-aided design*

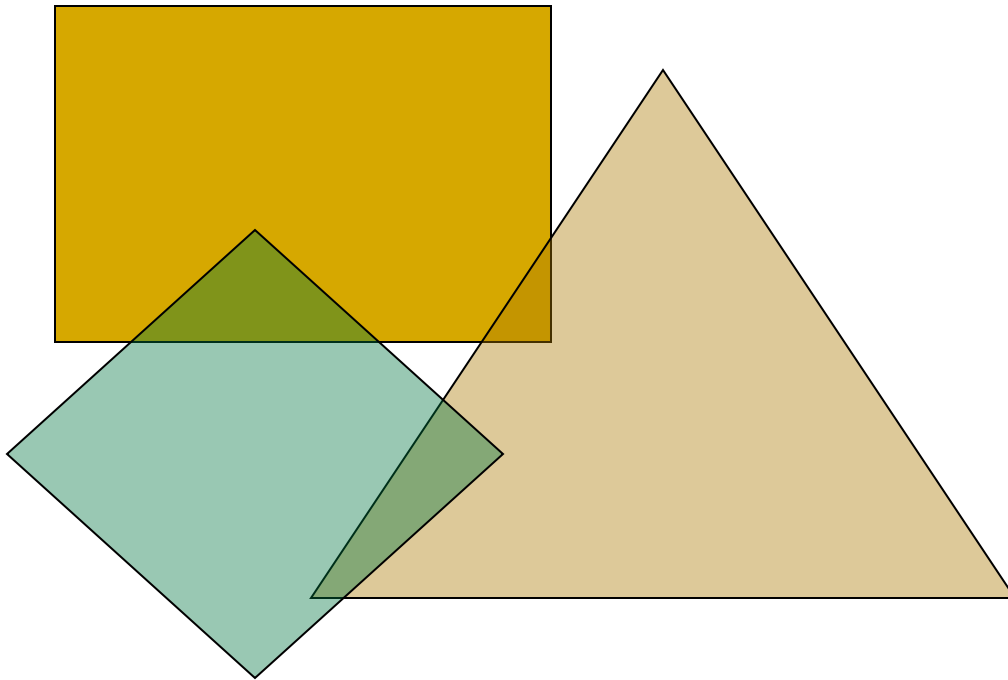


In this Course: Arrangements of lines



In this Course: *Arrangements of lines*

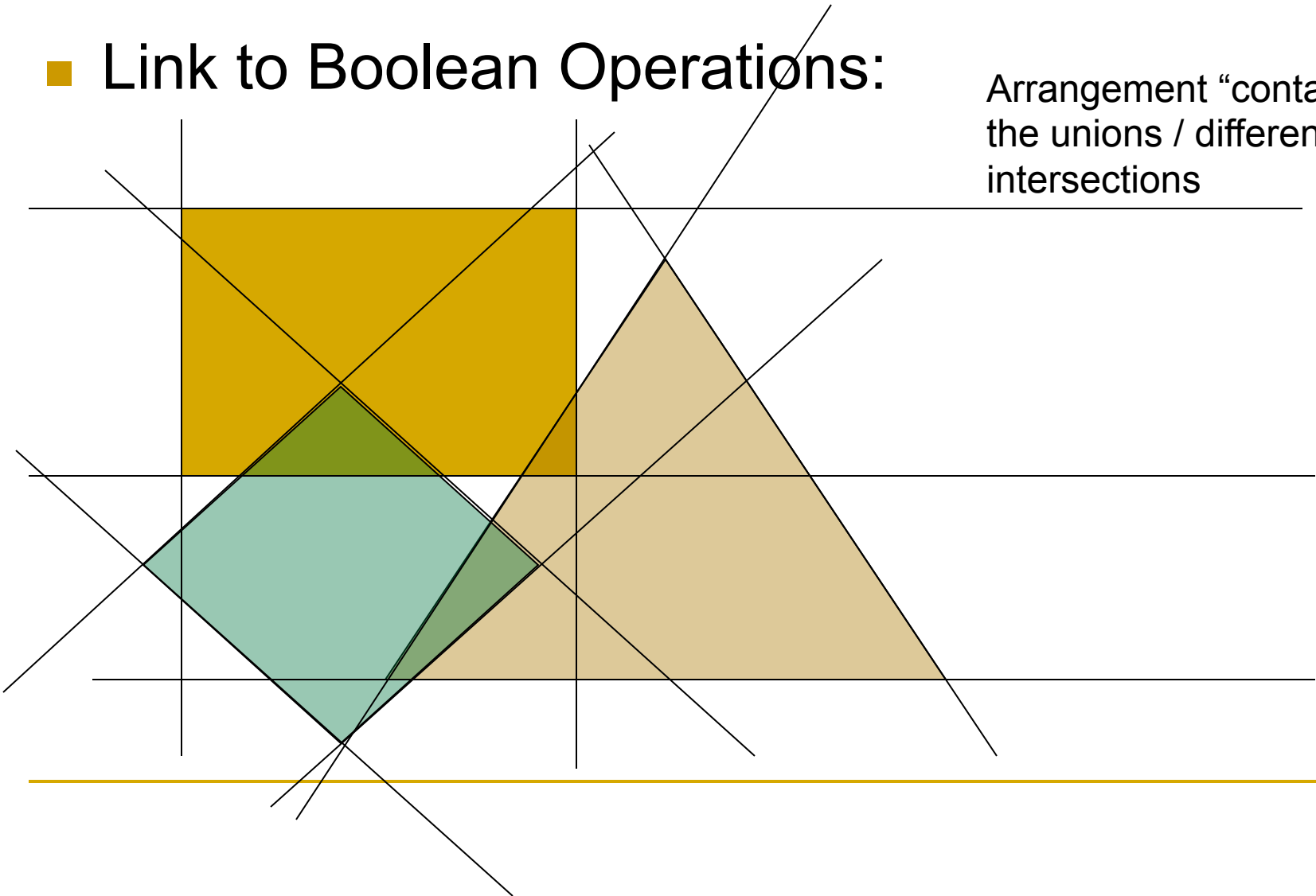
- Link to Boolean Operations:



In this Course: Arrangements of lines

- Link to Boolean Operations:

Arrangement “contains” all the unions / differences / intersections



In this Course:

Topic Overview

- Convex Hulls
 - Line Sweep (design pattern)
 - for segment intersections
 - Triangulations
 - of point sets
 - Delaunay Triangulations
 - Point Location
 - Trapezoidal Maps
 - Voronoi Diagrams
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In this Course:

Topic Overview

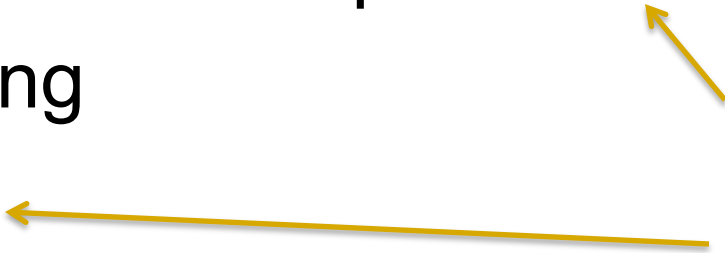
- Pseudotriangulations
 - Linear Programming
 - Smallest Enclosing Balls
 - Line Arrangements
 - Davenport-Schinzel sequences
 - Motion planning
 - Epsilon Nets
-

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Topic Overview

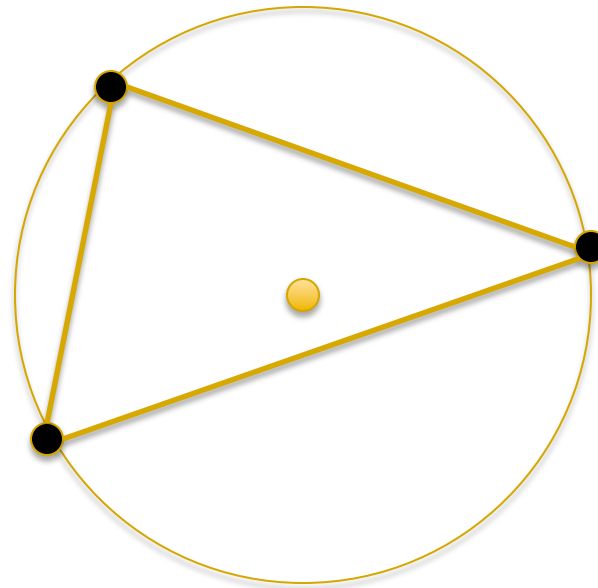
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discrete and
combinatorial
geometry



A Teaser Puzzle

- Suppose that we independently choose three points uniformly at random from a circle. What is the probability that the triangle defined by them contains the center of the circle?



Formalities

- Weekly Exercise session + exercise sheets (marked, but not graded)
 - 3 graded homeworks, to be submitted in LaTeX (usually two weeks time) **30%**
 - Homeworks may include an oral presentation or a small research project
 - 30 minute oral exam, with 30 minutes preparation time; one question will be from the weekly exercise sheets; **70%**
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