

# Linear Algebra

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\* Please take a look at the  
typed lecture notes

Question: What do we do when we have a linear system without solutions?

linear system  $Ax = b$  but there is no  $x$  s.t.  $Ax = b$ .

e.g. too many equations.

Idea: try to find  $x$  as close as possible to being a solution.

→ find  $x$  s.t.  $Ax$  is as close to  $b$  as possible.

$\hat{x}$  solution of  $\min_{x \in \mathbb{R}^n} \|Ax - b\|$

( $A$  in  $m \times n$ )  $\hat{x} = \arg \min_{x \in \mathbb{R}^n} \|Ax - b\|$

what is the set of possible vectors  $y \in \mathbb{R}^m$  s.t.  $y = A\hat{x}$  for some  $\hat{x} \in \mathbb{R}^n$ ?

It's  $C(A)$

$$\hookrightarrow = a_1 \hat{x}_1 + \dots + a_n \hat{x}_n$$
$$A = \begin{bmatrix} a_1 & \dots & a_n \\ \vdots & & \vdots \\ \vdots & & \vdots \end{bmatrix}$$

So if  $\hat{x}$  is a solution of  $\min_{x \in \mathbb{R}^n} \|Ax - b\|$   
then  $p = A\hat{x}$  is the projection of  $b$  on  $C(A)$ .

$$\|x\| = \sqrt{x_1^2 + \dots + x_n^2}$$
$$\|x\|^2 = x^T x = x \cdot x = \langle x, x \rangle$$

then  $\hat{x}$  is a solution of the "normal equations"

$$A^T(b - A\hat{x}) = 0$$

$$A^T A \hat{x} = A^T b \quad (\text{normal equations})$$

\* if  $A^T A$  is invertible then  $\hat{x} = (A^T A)^{-1} A^T b$

Do

the normal equations always have solutions?  
(even when  $A^T A$  is not invertible)

Yes, because  $C(A^T A) = C(A^T)$   
(prove  $\rightarrow$  as HW)

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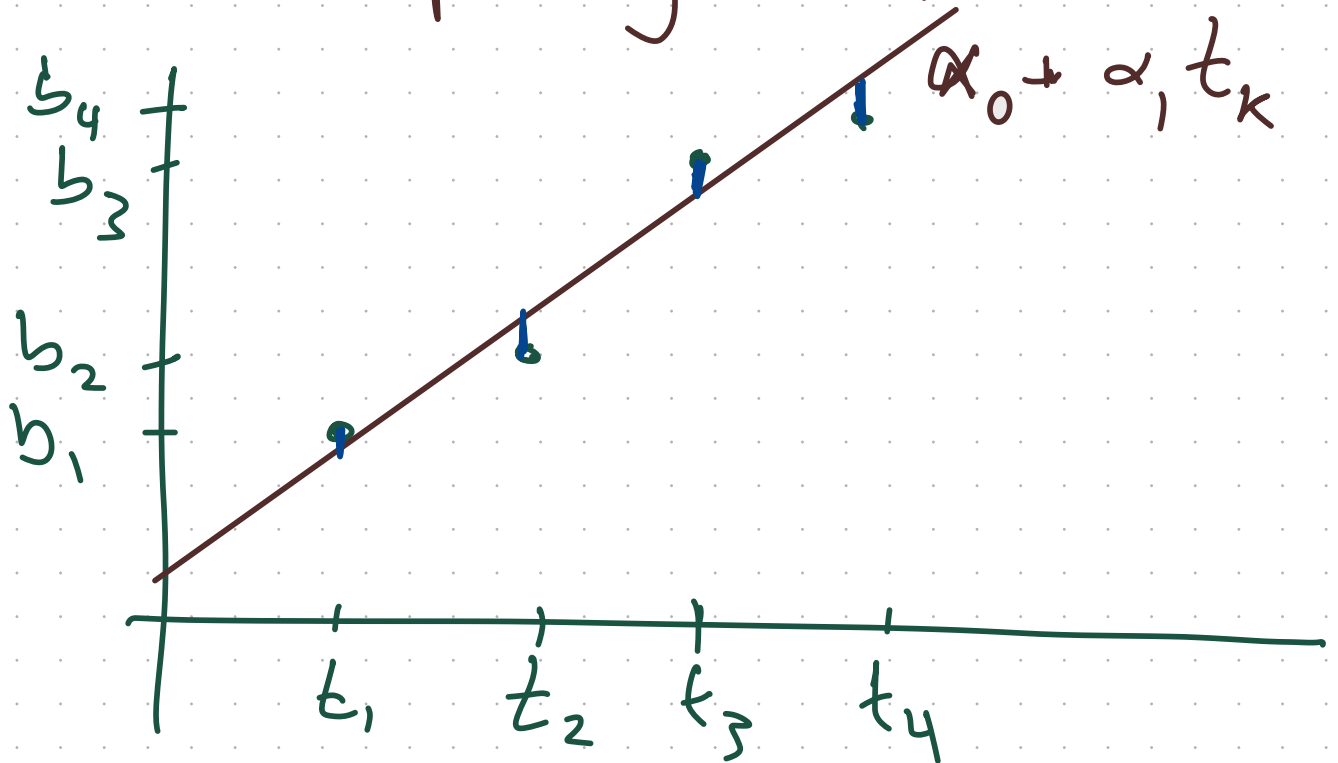
Theorem: for  $A$   $m \times n$  and  $b \in \mathbb{R}^m$  a solution  $\hat{x}$   
of  $\min_{x \in \mathbb{R}^n} \|Ax - b\|$  is also a solution of  
 $A^T A \hat{x} = A^T b$  (and vice-versa)

and if  $A$  has ind col. then  $\hat{x} = (A^T A)^{-1} A^T b$ .

Linear Regression:

data points  $(t_1, b_1), (t_2, b_2), \dots, (t_m, b_m)$   
(e.g.  $b_k$  is temp at time  $t_k$  in some experiment)

Let's say we suspect  $b_k$  has close to a linear dependency on  $t_k$



(\*)  $b_k \approx \alpha_0 + \alpha_1 t_k$  for some  $\alpha_0, \alpha_1 \in \mathbb{R}$

idea: find the best fit

$$(!!) \quad \min_{\alpha_0, \alpha_1} \sum_{k=1}^m \left( \underbrace{b_k}_{\text{"target"}} - \underbrace{(\alpha_0 + \alpha_1 t_k)}_{\text{"prediction"}} \right)^2$$

$$(\#) \quad \begin{bmatrix} b_1 \\ b_2 \\ \vdots \\ b_m \end{bmatrix} \approx \begin{bmatrix} 1 & t_1 \\ \vdots & \vdots \\ 1 & t_m \end{bmatrix} \begin{bmatrix} \alpha_0 \\ \alpha_1 \end{bmatrix} = \begin{bmatrix} \alpha_0 + \alpha_1 t_1 \\ \vdots \\ \alpha_0 + \alpha_1 t_m \end{bmatrix}$$

$$\mathbb{R}^m \ni b \approx A \begin{bmatrix} \alpha_0 \\ \alpha_1 \end{bmatrix} \quad \text{when } A = \begin{bmatrix} 1 & t_1 \\ \vdots & \vdots \\ 1 & t_m \end{bmatrix}$$

$$(!!) \quad \min_{\alpha_0, \alpha_1} \| b - A \begin{bmatrix} \alpha_0 \\ \alpha_1 \end{bmatrix} \|^2$$

We can solve (!!) by solving

$$A^T A \begin{bmatrix} \hat{\alpha}_0 \\ \hat{\alpha}_1 \end{bmatrix} = A^T b$$

if  $A^T A$  is inv the

$$\begin{bmatrix} \hat{\alpha}_0 \\ \hat{\alpha}_1 \end{bmatrix} = (A^T A)^{-1} A^T b$$

$$A = \begin{bmatrix} 1 & t_1 \\ \vdots & \vdots \\ 1 & t_m \end{bmatrix}$$

$$A^T A = \begin{bmatrix} m & \sum_{k=1}^m t_k \\ \sum_{k=1}^m t_k & \sum_{k=1}^m t_k^2 \end{bmatrix}$$

$$\begin{bmatrix} 1 & \dots & 1 \end{bmatrix} \begin{bmatrix} 1 \\ \vdots \\ 1 \end{bmatrix} = m \quad \begin{bmatrix} t_1 & \dots & t_m \end{bmatrix} \begin{bmatrix} t_1 \\ \vdots \\ t_m \end{bmatrix} = \sum t_k^2$$

when would it be that A doesn't have ind. col.

if  $t_k = t \forall k$  (all  $t_k$ 's are equal)

degenerate situation in Linear Regression.

$$A^T A = \begin{bmatrix} m & mt \\ mt & mt^2 \end{bmatrix}$$

So lin dep.

HW: Is this the only situation in which  $A^T A$  is not inv?

if  $A^T A$  is inv

$$\begin{bmatrix} \hat{\alpha}_0 \\ \hat{\alpha}_1 \end{bmatrix} = \begin{bmatrix} m & \sum t_k \\ \sum t_k & \sum t_k^2 \end{bmatrix}^{-1} A^T b$$

if  $\sum t_k = 0$

(via change of variables  
 $t^{\text{new}} = t - \frac{1}{m} \sum t_k$ )

$$\begin{bmatrix} \hat{\alpha}_0 \\ \hat{\alpha}_1 \end{bmatrix} = \begin{bmatrix} m & 0 \\ 0 & \sum t_k^2 \end{bmatrix}^{-1} A^T b$$

$$= \begin{bmatrix} \frac{1}{m} & 0 \\ 0 & \frac{1}{\sum t_k^2} \end{bmatrix} \begin{bmatrix} \sum b_k \\ \sum t_k b_k \end{bmatrix}$$
$$= \begin{bmatrix} \frac{1}{m} \sum b_k \\ \frac{\sum t_k b_k}{\sum t_k^2} \end{bmatrix}$$

(HW: inv diag matrix is easy)

Fit a Parabola

$$b_k \approx \alpha_0 + \alpha_1 t_k + \alpha_2 t_k^2$$

$$b = \begin{bmatrix} b_1 \\ \vdots \\ b_m \end{bmatrix} \quad \alpha = \begin{bmatrix} \alpha_0 \\ \alpha_1 \\ \alpha_2 \end{bmatrix}$$

$$b \approx \begin{bmatrix} 1 & t_1 & t_1^2 \\ 1 & t_2 & t_2^2 \\ 1 & t_3 & t_3^2 \\ \vdots & \vdots & \vdots \\ 1 & t_m & t_m^2 \end{bmatrix} \begin{bmatrix} \alpha_0 \\ \alpha_1 \\ \alpha_2 \end{bmatrix}$$

Now do  
least squares.

MW:  $\rightarrow$  When is it that  $A^T A$  is not invertible for this  $A$ ?

$\rightarrow$  how could we make  $A^T A$  a diag. matrix?

CS Lens:

$$b_k \approx 3\alpha_0 + (t_k - 5)\alpha_1 + (t_k^2 + t_k)\alpha_2$$

CS Lens: kernel Methods