

# Linear Algebra

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\* Please take a look at the  
typed lecture notes

\* The full notes are now available!!

## Last Lecture:

$L$ , written in the basis  $u_1, \dots, u_n$  and  $v_1, \dots, v_m$  is described by the matrix  $V^{-1}AU$ , where  $A$  is the matrix representing  $L$  in the canonical basis.

$L: \mathbb{R}^n \longrightarrow \mathbb{R}^m$  linear transf.

$$L\left(\sum_{j=1}^n x_j e_j\right) = \sum_{i=1}^m (Ax)_i e_i \quad x = \begin{bmatrix} x_1 \\ \vdots \\ x_n \end{bmatrix}$$

$$L\left(\sum_{j=1}^n \alpha_j u_j\right) = \sum_{i=1}^m (B\alpha)_i v_i \quad \alpha = \begin{bmatrix} \alpha_1 \\ \vdots \\ \alpha_n \end{bmatrix}$$

$$B = V^{-1}AU$$

This is called the change of basis of a linear transformation.

back to  $n \times n$  matrices.

$A \in \mathbb{R}^{n \times n}$  has a complete set of eigenvectors.

$v_1, \dots, v_n$  eigenvectors of  $A$   
basis of  $\mathbb{R}^n$ .

any vector  $v$  can be written as

$$v = \sum \alpha_i v_i$$

$$Av = \sum \alpha_i Av_i = \sum \alpha_i \lambda_i v_i$$

$$A^10 v = \sum \alpha_i A^10 v_i = \sum \alpha_i \lambda_i^{10} v_i.$$

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Theorem 6.2.1. Let  $A \in \mathbb{R}^{n \times n}$  with a complete set of real eigenvectors  $v_1, \dots, v_n$  and associated eigenvalues  $\lambda_1, \dots, \lambda_n \in \mathbb{R}$ .

Let  $V \in \mathbb{R}^{n \times n}$  be the matrix with columns

$$v_1, \dots, v_n \quad V = \begin{bmatrix} | & & | \\ v_1 & \dots & v_n \\ | & & | \end{bmatrix}$$

$$A = V \Lambda V^{-1} \quad (1)$$

where  $\Lambda$  is an  $n \times n$  diagonal matrix with  $\lambda_1, \dots, \lambda_n$  in the diagonal.

Proof:  $v_1, \dots, v_n$  is a basis thus  $V$  is invertible.

it is enough to show

$$V^{-1} A V = \Lambda$$

$$\begin{aligned} V^{-1} A V = \Lambda &\Leftrightarrow \\ V V^{-1} A V = V \Lambda &\Leftrightarrow \\ V V^{-1} A V V^{-1} = V \Lambda V^{-1} &\Leftrightarrow \\ A = V \Lambda V^{-1} & \end{aligned}$$

let's see what is the  $j$ -th column of  $V^{-1} A V$ .

$$\begin{aligned} (V^{-1} A V)_j &= V^{-1} A V e_j = V^{-1} A v_j = \\ &= V^{-1} \lambda_j v_j = \lambda_j V^{-1} v_j = \lambda_j e_j \end{aligned}$$

$$V^{-1} A V = \begin{bmatrix} \lambda_1 & & & & \\ & \lambda_2 & & & \\ & & \ddots & & \\ & & & \lambda_j & \\ & & & & \ddots \\ & & & & & \lambda_n \end{bmatrix} \begin{matrix} \leftarrow j\text{-th row} \\ \leftarrow j\text{-th} \end{matrix} = \Lambda$$

$$V^{-1} V = \begin{bmatrix} 1 & & & 0 \\ & \ddots & & \\ & & 1 & \\ 0 & & & \ddots \end{bmatrix} \begin{matrix} \uparrow \\ \uparrow \\ \uparrow \\ \leftarrow j\text{-th} \end{matrix}$$

Def: If we can do the above:

6.2.2.  $A$  is diagonalizable.

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Def 6.2.3. We say  $A \in \mathbb{R}^{n \times n}$  and  $B \in \mathbb{R}^{n \times n}$  are similar matrices if there exists  $S$   $n \times n$  invertible s.t.

$$B = S^{-1} A S.$$

Prop 6.2.4. Similar matrices have the same eigenvalues.

Proof: HW (see Chalky 64 and 65)

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Theorem 6.3.1 [Spectral Theorem]

Any Symmetric matrix  $A \in \mathbb{R}^{n \times n}$ ,  $A^T = A$  has a complete set of real eigenvectors and they can be made orthonormal.  
(and has  $n$  real eigenvalues, up to repetition).

(if  $B \in \mathbb{R}^{m \times n}$  not symmetric,  $B^T B$  and  $B B^T$  are symmetric)

Corollary 6.3.3.

If  $A \in \mathbb{R}^{n \times n}$  is symmetric.

$$A = V \Lambda V^T \quad (2)$$

where  $V = \begin{bmatrix} | & & | \\ v_1 & \dots & v_n \\ | & & | \end{bmatrix}$  matrix with  $n$  orthonormal eigenvectors of  $A$ , and  $\Lambda$  diag with  $\Lambda_{ii} = \lambda_i$ .

Remarks 6.3.3. (1) and (2) and (3).  
eigenvalue positions.

Cor. 6.3.4.  $A \in \mathbb{R}^{n \times n}$  sym.

$\text{rank}(A) = \#$  non-zero e-values of  $A$   
(counting repetitions)

Prop 6.3.6.  $A \in \mathbb{R}^{n \times n}$  sym.  $v_1, \dots, v_n$  orthonormal basis of e-vectors,  $\lambda_1, \dots, \lambda_n$  corresponding e-values

$$A = \sum_{k=1}^n \lambda_k \underbrace{v_k v_k^T}_{\text{rank 1.}} \quad (3)$$

HW: prove this.

Prop 6.3.7. Let  $A \in \mathbb{R}^{n \times n}$  sym. Let  $\lambda \in \mathbb{C}$  be an eigenvalue of  $A$ . then  $\lambda \in \mathbb{R}$ .

Proof: Let  $v \in \mathbb{C}^n$  be an e-vector of  $A$  associated with  $\lambda$ .

real  $M^* = \overline{M}^T$  since  $A \in \mathbb{R}^{n \times n}$  and sym

$$Av = \lambda v$$

$$A^* = \overline{A}^T = A^T = A$$

$$= v^* Av = v^* (\lambda v) = \lambda v^* v = \lambda \|v\|^2$$

$$= (\lambda v)^* v = (Av)^* v = v^* A^* v = v^* Av =$$

$$= \overline{\lambda} v^* v = \overline{\lambda} \|v\|^2$$

$$\lambda \|v\|^2 = \overline{\lambda} \|v\|^2$$

$$\Leftrightarrow \lambda = \overline{\lambda}$$

$$\Leftrightarrow \lambda \in \mathbb{R}.$$

Obs: True for  $A \in \mathbb{C}^{n \times n}$  s.t.  $A^* = A$ .  
A Hermitian.

Cor 6.3.8 Every real symmetric matrix has a real eigenvalue.

Remark 6.3.9.1

$A \in \mathbb{R}^{n \times n}$  sym.

$v_1$  and  $v_2$  e-vectors of  $A$  with dif. e-values  $\lambda_1, \lambda_2 \in \mathbb{R}$ .

$$\begin{aligned} \lambda_1 v_1^T v_2 &= (\lambda_1 v_1)^T v_2 = (A v_1)^T v_2 = v_1^T A^T v_2 = v_1^T A v_2 = v_1^T \lambda_2 v_2 \\ &= \lambda_2 v_1^T v_2 \end{aligned}$$

$$\lambda_1 v_1^T v_2 = \lambda_2 v_1^T v_2$$

$$\lambda_1 \neq \lambda_2$$

$$\implies v_1^T v_2 = 0.$$

$$v_1 \perp v_2.$$



# Proof of Spectral Theorem.

$A \in \mathbb{R}^{n \times n}$  sym.

- For any  $1 \leq k \leq n$ ,  $A$  has  $k$  orthonormal eigenvectors.

$k = n$  gives us our Thm.

Let's use induction.

→  $k = 1$ . By Cor 6.3.8 there is a real eigenvector and we can normalize it to have norm 1.

→ Assuming we have  $v_1, \dots, v_k$  orthonormal eigenvectors of  $A$  (with eigenvalues  $\lambda_1, \dots, \lambda_k$ ) we will show we can "add" one more  $v_{k+1}$ .

Let  $u_{k+1}, \dots, u_n$  be an orthonormal basis

for the orthogonal complement of the span of  $v_1, \dots, v_k$ .

$v_1, \dots, v_k, u_{k+1}, \dots, u_n$  is an orthonormal basis of  $\mathbb{R}^n$

$V$   $n \times n$  matrix  $V = \begin{bmatrix} | & & & & | \\ v_1 & \dots & v_k & u_{k+1} & \dots & u_n \\ | & & & & | \end{bmatrix}$

$$V^T V = I, \quad V V^T = I.$$

$$B = V^T A V = \begin{bmatrix} \text{---} & v_1^T & \text{---} \\ \text{---} & \vdots & \text{---} \\ \text{---} & v_k^T & \text{---} \\ \text{---} & u_{k+1}^T & \text{---} \\ \text{---} & \vdots & \text{---} \\ \text{---} & u_n^T & \text{---} \end{bmatrix} \begin{bmatrix} | & & & & | \\ Av_1 & Av_2 & \dots & Av_k & Au_{k+1} & \dots \\ | & & & & | \end{bmatrix}$$

$$= \begin{bmatrix} \text{---} & v_1^T & \text{---} \\ \text{---} & \vdots & \text{---} \\ \text{---} & v_k^T & \text{---} \\ \text{---} & u_{k+1}^T & \text{---} \\ \text{---} & \vdots & \text{---} \\ \text{---} & u_n^T & \text{---} \end{bmatrix} \begin{bmatrix} | & & & & | \\ \lambda_1 v_1 & \dots & \lambda_k v_k & Au_{k+1} & \dots \\ | & & & & | \end{bmatrix} = \begin{array}{l} \text{Nice Nice} \\ \text{Nice Term!} \end{array}$$