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# Lecture 21: Projections of sets and the Farkas Lemma



## The strategy

### The guiding question

Suppose we are given a set of linear inequalities in  $\mathbb{R}^n$ . How can we certify that the set is nonempty?

### Definition (Projection of a set of inequalities)

Let  $A \in \mathbb{Q}^{m \times n}$ ,  $b \in \mathbb{Q}^m$  and  $P = \{x \in \mathbb{R}^n \mid Ax \le b\}$ . *P* is called a polyhedron. Let  $S = \{1, ..., s\}$ . The **projection of P** on the subspace  $\mathbb{R}^s$  associated with the variables in the subset *S* is

 $\operatorname{proj}_{\mathcal{S}}(\mathcal{P}) := \{ x \in \mathbb{R}^s \mid \exists y \in \mathbb{R}^{n-s} \text{ such that } (x^T, y^T)^T \in \mathcal{P} \}.$ 

### Remark / Question

- $P \neq \emptyset$  if and only if  $\operatorname{proj}_{\mathcal{S}}(P) \neq \emptyset$ .
- Does proj<sub>S</sub>(P) have a description in form of a finite system of linear inequalities?
- If so, then the question whether P ≠ Ø is reduced to a question of the same form in smaller dimension.

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## The one-dimensional case

### Intuition

Let  $a \in \mathbb{Q}^m$ ,  $a_i \neq 0$  for all *i* and  $b \in \mathbb{Q}^m$ . We consider  $P = \{x \in \mathbb{R} \mid ax \le b\} \subseteq \mathbb{R}$ . We first notice that we can rewrite the constraints in *P* as follows. Set

$$u := \min\{\frac{b_i}{a_i} \mid a_i > 0\}, \quad I := \max\{\frac{b_i}{a_i} \mid a_i < 0\}.$$

$$P = \{x \in \mathbb{R} \mid x \leq \frac{b_i}{a_i} \text{ if } a_i > 0, \ x \geq \frac{b_i}{a_i} \text{ if } a_i < 0\} = \{x \in \mathbb{R} \mid x \leq u, \ x \geq l\}.$$

### Proposition

$$P \neq \emptyset \iff I \leq u \iff 0 \leq u - I \iff 0 \leq y^T b$$
 for all  $y \geq 0$  such that  $y^T a = 0$ .

### We want to derive such a result in general dimensions!

Let  $A \in \mathbb{Q}^{m \times n}$  with entries  $a_{ij}$ , let  $b \in \mathbb{Q}^m$  and  $P = \{x \in \mathbb{R}^n \mid Ax \le b\}$ . Let  $\bar{x} = (x_1, \dots, x_{n-1})$  and  $\bar{A} = [A_{\cdot 1} \dots A_{\cdot n-1}]$ .

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## Elimination of one variable

### Algorithm

(1) Partition the indices  $M = \{1, ..., m\}$  of the rows of A into three subsets

$$M_0 = \{i \in M \mid a_{i,n} = 0\}, \quad M_+ = \{i \in M \mid a_{i,n} > 0\} \text{ and } M_- = \{i \in M \mid a_{i,n} < 0\}.$$

(2) • For every row with index  $i \in M_+$  multiply the corresponding constraint by  $\frac{1}{a_i}$ .

$$x_n \leq d_i + f_i^T ar{x}$$
 for  $i \in M_+$  where  $d_i = rac{b_i}{a_{in}}, \ f_{ij} = -rac{a_{ij}}{a_{in}}$ 

Every row with index k ∈ M<sub>0</sub> can be rewritten as

$$0 \le d_k + f_k^T \bar{x}$$
 for  $k \in M_0$  where  $d_k = b_k$ ,  $f_{kj} = -a_{kj}$ .

• For every row with index  $i \in M_{-}$  multiply the corresponding constraint by  $\frac{1}{a_{in}}$ .

$$\mathbf{x}_n \geq \mathbf{d}_i + \mathbf{f}_i^T ar{\mathbf{x}}$$
 for  $i \in M_-$  where  $\mathbf{d}_i = rac{\mathbf{b}_i}{\mathbf{a}_{in}}, \ \mathbf{f}_{ij} = -rac{\mathbf{a}_{ij}}{\mathbf{a}_{in}}$ 

#### (3) Return Q.

## Elimination of one variable continued

$$\begin{aligned} Q &= & \left\{ \bar{x} \in \mathbb{R}^{n-1} \mid & 0 \leq & d_k + f_k^T \bar{x} \text{ for all } k \in M_0, \\ & d_l + f_l^T \bar{x} & \leq & d_l + f_i^T \bar{x} \text{ for all } l \in M_-, \ i \in M_+ \right\}. \end{aligned}$$

### Theorem 3. Let $S = \{1, ..., n-1\}$

The set *Q* returned in Step 3 is a polyhedron. Moreover,  $Q = \text{proj}_{S}(P)$ .

### Proof of the first statement

• *Q* is a polyhedron, because we find  $F \in \mathbb{Q}^{k \times n-1}$  and  $f \in \mathbb{Q}^k$  such that

$$Q = \Big\{ \bar{x} \in \mathbb{R}^{n-1} \mid F\bar{x} \leq f \Big\}.$$

- Let  $k = |M_0| + |M_-||M_+|$ . The rows of *F* contain all rows of *A* with index  $i \in M_0$ . The corresponding right hand side vector satisfies that  $f_i = b_i$ .
- The other rows of *F* are of the form  $(f_l f_i)^T$  for indices  $l \in M_-$  and  $i \in M_+$ . The corresponding right hand side entry of *f* is then  $d_i d_l$ .

## **Proof continued**

### $\operatorname{proj}_{\mathcal{S}}(P) \subseteq Q.$

Take any  $\bar{x} \in \operatorname{proj}_{S}(P)$ . There exists  $z \in \mathbb{R}$  such that  $(\bar{x}, z) \in P$ . Hence z satisfies the constraints in Step 2. In particular,

$$d_l + f_l^T \bar{x} \leq z \leq d_i + f_i^T \bar{x}$$
 for all  $l \in M_-$ ,  $i \in M_+$ .

This shows that  $\bar{x} \in Q$ .

### $Q \subseteq \operatorname{proj}_{\mathcal{S}}(P)$

Take any  $\bar{x} \in Q$ . It follows that

$$\begin{array}{lll} 0 & \leq & d_k + f_k^T \bar{x} \text{ for all } k \in M_0, \\ d_l + f_l^T \bar{x} & \leq & d_l + f_l^T \bar{x} \text{ for all } l \in M_-, \ i \in M_+ \Big\}. \end{array}$$

Let  $L := \max\{d_l + f_l^T \bar{x} \mid l \in M_-\}$  and  $U := \min\{d_i + f_i^T \bar{x} \mid i \in M_+\}$ . Take any value  $z \in [L, U]$ . Then  $(\bar{x}, z) \in P$ . Hence,  $\bar{x} \in \operatorname{proj}_{\mathcal{S}}(P)$ .

# Use these projections repeatedly

#### Lemma

Let  $A \in \mathbb{Q}^{m \times n}$ ,  $b \in \mathbb{Q}^m$  and  $P = \{x \in \mathbb{R}^n \mid Ax \le b\}$ . For indices  $1 \le k < j < n$ , consider

$$S_1 = \{1, \dots, n-k\}$$
 and  $S_2 = \{1, \dots, n-j\}$ .

Then  $\operatorname{proj}_{S_2}(P) = \operatorname{proj}_{S_2}(\operatorname{proj}_{S_1}(P)).$ 

#### Proof for k = 1 and j = 2

 Let z ∈ proj<sub>S2</sub>(P). There exist (x<sub>n-1</sub>, x<sub>n</sub>) ∈ ℝ<sup>2</sup> such that (z, x<sub>n-1</sub>, x<sub>n</sub>) ∈ P. In particular, there exists a value x<sub>n</sub> such that

$$(z, x_{n-1}, x_n) \in P \quad \Rightarrow \quad (z, x_{n-1}) \in \operatorname{proj}_{S_1}(P) \quad \Rightarrow \quad z \in \operatorname{proj}_{S_2}(\operatorname{proj}_{S_1}(P)).$$

• Conversely, take  $z \in \operatorname{proj}_{S_2}(\operatorname{proj}_{S_1}(P))$ , i.e., there exists  $x_{n-1} \in \mathbb{R}$  such that

$$(z, x_{n-1}) \in \operatorname{proj}_{S_1}(P).$$

Hence there exists  $x_n \in \mathbb{R}$  such that  $(z, x_{n-1}, x_n) \in P$ , i.e.,  $z \in \operatorname{proj}_{S_2}(P)$ .

## The elimination process algebraically

### **Definition 5**

Let  $A \in \mathbb{Q}^{m \times n}$ ,  $b \in \mathbb{Q}^m$  and  $P = \{x \in \mathbb{R}^n \mid Ax \le b\}$ . We define  $A^{(j)}$  to be the submatrix of A with column vectors  $A_{\cdot,k}$  for k = 1, ..., j. Let  $P^{(0)} = P$  and  $C^{(0)} = \mathbb{R}^m_+$ .

Define for  $i \in \{1, \ldots, n\}$ 

$$C^{(i)} = \left\{ y \in \mathbb{R}^m_+ \mid y^T A_{\cdot k} = 0 \text{ for all } k = n - i + 1, \dots, n \right\}.$$
$$P^{(i)} = \left\{ \bar{x} \in \mathbb{R}^{n-i} \mid y^T A^{(n-i)} \bar{x} \le y^T b \text{ for all } y \in C^{(i)} \right\}.$$

### Theorem

- $\operatorname{proj}_{S_{n-i}}(P) = P^{(i)}$ .
- The proof shows that P<sup>(i)</sup> is a polyhedron
- Polyhedra are closed under projections.

## First part of the proof

# $\operatorname{proj}_{\mathcal{S}_{n-i}}(\mathcal{P}) \subseteq \mathcal{P}^{(i)}$

• Let  $\bar{x} \in \operatorname{proj}_{S_{n-i}}(P)$ . By definition, there exists  $z \in \mathbb{R}^i$  such that

$$(\bar{x},z)\in P.$$

• Hence,  $(\bar{x}, z)$  satisfies the following inequalities

$$\sum_{k=1}^{n-i} A_{\cdot k} \bar{x}_k + \sum_{k=n-i+1}^n A_{\cdot k} z_k \leq b.$$

• This implies that for all  $y \in C^{(i)}$  we obtain that

$$\begin{split} \sum_{k=1}^{n-i} y^T A_{\cdot k} \bar{x}_k + \sum_{k=n-i+1}^n y^T A_{\cdot k} z_k &= \sum_{k=1}^{n-i} y^T A_{\cdot k} \bar{x}_k \\ &= y^T A^{(n-i)} \bar{x} \leq y^T b, \end{split}$$



# Second part of the proof

# $P^{(i)} \subseteq \operatorname{proj}_{S_{n-i}}(P).$

• We apply an inductive argument. The base case is *i* = 1. Recall

$$\begin{aligned} &\mathcal{C}^{(1)} &= & \Big\{ y \in \mathbb{R}^m_+ \mid y^T \mathcal{A}_{.n} = 0 \Big\}, \\ &\mathcal{P}^{(1)} &= & \Big\{ \bar{x} \in \mathbb{R}^{n-1} \mid y^T \mathcal{A}^{(n-1)} \bar{x} \leq y^T b \text{ for all } y \in \mathcal{C}^{(1)} \Big\}. \end{aligned}$$

•  $P^{(1)} \subseteq \operatorname{proj}_{S_{n-1}}(P)$  follows by observing:

- if one takes y as the unit vector  $e_k$  for  $k \in M_0$ . Then  $e_k \in C^{(1)}$ .
- pick two indices  $I \in M_{-}$  and  $i \in M_{+}$ . Then

$$y := -\frac{1}{a_{ln}}e_l + \frac{1}{a_{in}}e_i \in C^{(1)}.$$

- The corresponding inequalities obtained from choosing y as described above are part of the description of Q = proj<sub>S<sub>n-1</sub></sub>(P) in Theorem 3.
- The inductive step can be shown similarly.

### Theorem (The Farkas Lemma)

Let  $A \in \mathbb{Q}^{m \times n}$ ,  $b \in \mathbb{Q}^m$ . Either there exists a vector  $x \in \mathbb{R}^n$  such that  $Ax \leq b$  or there exists a vector  $y \in \mathbb{R}^m$  such that  $y \geq 0$ ,  $y^T A = 0$  and  $y^T b < 0$ .

### Proof.

We refer to the notation introduced in Definition 5.

$$C^{(n)} = \{ y \in \mathbb{R}^{m}_{+} \mid y^{T} A_{j} = 0 \text{ for all } j = 1, \dots, n \} = \{ y \ge 0 \mid y^{T} A = 0 \}$$

 $P^{(n)} = \{ 0 \le y^T b \text{ for all } y \in C^{(n)} \}.$  We conclude that

$$P \neq \emptyset \iff P^{(1)} \neq \emptyset \iff \ldots \iff P^{(n)} \neq \emptyset \iff y^T b \ge 0 \forall y \ge 0 \text{ with } y^T A = 0.$$

Either  $P \neq \emptyset$  or  $P = \emptyset$ . Equivalently: either there exists

 $x \in \mathbb{R}^n$  such that  $Ax \le b$  or  $y \in \mathbb{R}^m$  such that  $y \ge 0$ ,  $y^T A = 0$  and  $y^T b < 0$ .